

KONRAD Family Name	A. Given Name	Prof. Student Number
------------------------------	-------------------------	--------------------------------

Please Insert Your **Name in Full and Student Number**

- (1) Consider a *spherical* coordinate system (r, θ, ϕ) in which point P is located at $(50\text{m}, 60^\circ, 30^\circ)$ and point P' is located at $(42\text{m}, 30^\circ, 45^\circ)$. The position vectors of P and P' in the *spherical* coordinate system are $\mathbf{r} = 50\hat{\mathbf{a}}_r$ [m] and $\mathbf{r}' = 42\hat{\mathbf{a}}_r$ [m], respectively. Find

- (a) the position vectors \mathbf{r} and \mathbf{r}' in the *Cartesian* coordinate system.
- (b) the distance vector $\mathbf{R} = \mathbf{r} - \mathbf{r}'$ in the *Cartesian* coordinate system.
- (c) the distance vector $\mathbf{R} = \mathbf{r} - \mathbf{r}'$ at point P in the *spherical* coordinate system
- (d) the distance vector $\mathbf{R} = \mathbf{r} - \mathbf{r}'$ at point P' in the *spherical* coordinate system

Hint: Make use of the Table given below.

- (2) A circular ring of radius a [m] carries a uniform charge ρ_L [C/m] and is placed on the xy-plane with axis the same as the z-axis. **Without invoking symmetry**, i.e. only by making use of vector calculus, show that in a *cylindrical* coordinate system the ρ -component of the electric field at points on the axis of the ring (z-axis) is zero.

(1) Solution:¹

- (a) In the *Cartesian* coordinate system:

$$\begin{aligned} \mathbf{P} &= [50\sin(60^\circ)\cos(30^\circ), 50\sin(60^\circ)\sin(30^\circ), 50\cos(60^\circ)] = (37.50, 21.65, 25.00) \\ \mathbf{r} &= 37.50\hat{\mathbf{a}}_x + 21.65\hat{\mathbf{a}}_y + 25.00\hat{\mathbf{a}}_z \text{ [m]} \end{aligned}$$

$$\begin{aligned} \mathbf{P}' &= [42\sin(30^\circ)\cos(45^\circ), 42\sin(30^\circ)\sin(45^\circ), 42\cos(30^\circ)] = (14.85, 14.85, 36.37) \\ \mathbf{r}' &= 14.85\hat{\mathbf{a}}_x + 14.85\hat{\mathbf{a}}_y + 36.37\hat{\mathbf{a}}_z \text{ [m]} \end{aligned}$$

- (b) In the *Cartesian* coordinate system:

$$\begin{aligned} \mathbf{R} = \mathbf{r} - \mathbf{r}' &= 37.50\hat{\mathbf{a}}_x + 21.65\hat{\mathbf{a}}_y + 25.00\hat{\mathbf{a}}_z - 14.85\hat{\mathbf{a}}_x - 14.85\hat{\mathbf{a}}_y - 36.37\hat{\mathbf{a}}_z \\ &= 22.65\hat{\mathbf{a}}_x + 6.80\hat{\mathbf{a}}_y - 11.37\hat{\mathbf{a}}_z \text{ [m]} \\ &= R_x\hat{\mathbf{a}}_x + R_y\hat{\mathbf{a}}_y + R_z\hat{\mathbf{a}}_z \text{ [m]} \end{aligned}$$

- (c) In the *spherical* coordinate system:

At P:

$$\begin{aligned} \mathbf{R} = \mathbf{r} - \mathbf{r}' &= [+ R_x \sin(\theta)\cos(\phi) + R_y \sin(\theta)\sin(\phi) + R_z \cos(\theta)] \hat{\mathbf{a}}_r \\ &\quad [+ R_x \cos(\theta)\cos(\phi) + R_y \cos(\theta)\sin(\phi) - R_z \sin(\theta)] \hat{\mathbf{a}}_\theta \\ &\quad [- R_x \sin(\phi) \quad + R_y \cos(\phi)] \hat{\mathbf{a}}_\phi \end{aligned}$$

¹ See textbook for relationship between vector components in Cartesian, cylindrical and spherical coordinate systems.

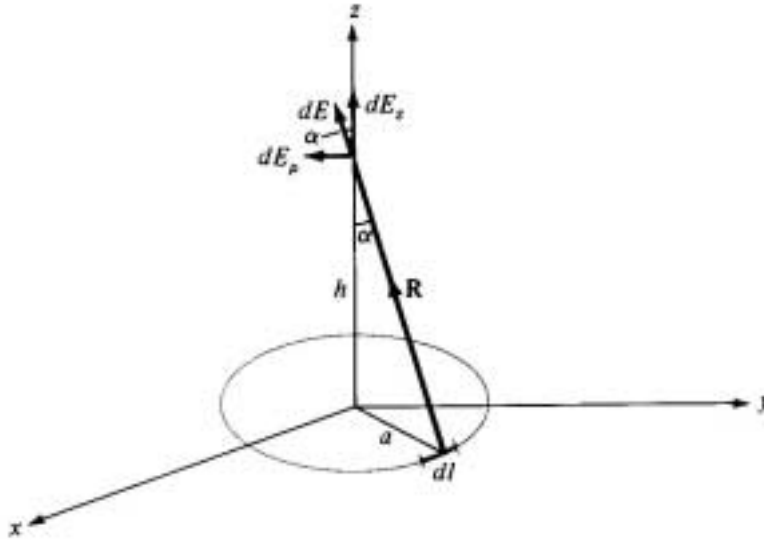
$$\begin{aligned}
&= [+22.65 \sin(60^\circ) \cos(30^\circ) + 6.80 \sin(60^\circ) \sin(30^\circ) - 11.37 \cos(60^\circ)] \hat{\mathbf{a}}_r \\
&\quad [+22.65 \cos(60^\circ) \cos(30^\circ) + 6.80 \cos(60^\circ) \sin(30^\circ) + 11.37 \sin(60^\circ)] \hat{\mathbf{a}}_\theta \\
&\quad [-22.65 \sin(30^\circ) + 6.80 \cos(30^\circ)] \hat{\mathbf{a}}_\phi \\
&= [16.99 + 2.94 - 5.69] \hat{\mathbf{a}}_r + [9.81 + 1.70 + 9.85] \hat{\mathbf{a}}_\theta + [-11.33 + 5.89] \hat{\mathbf{a}}_\phi \text{ [m]} \\
&= 14.24 \hat{\mathbf{a}}_r + 21.36 \hat{\mathbf{a}}_\theta - 5.44 \hat{\mathbf{a}}_\phi \text{ [m]}
\end{aligned}$$

(d) In the *spherical* coordinate system:

At P':

$$\begin{aligned}
\mathbf{R} = \mathbf{r} - \mathbf{r}' &= [+R_x \sin(\theta) \cos(\phi) + R_y \sin(\theta) \sin(\phi) + R_z \cos(\theta)] \hat{\mathbf{a}}_r \\
&\quad [+R_x \cos(\theta) \cos(\phi) + R_y \cos(\theta) \sin(\phi) - R_z \sin(\theta)] \hat{\mathbf{a}}_\theta \\
&\quad [-R_x \sin(\phi) \quad + R_y \cos(\phi)] \hat{\mathbf{a}}_\phi \\
&= [+22.65 \sin(30^\circ) \cos(45^\circ) + 6.80 \sin(30^\circ) \sin(45^\circ) - 11.37 \cos(30^\circ)] \hat{\mathbf{a}}_r \\
&\quad [+22.65 \cos(30^\circ) \cos(45^\circ) + 6.80 \cos(30^\circ) \sin(45^\circ) + 11.37 \sin(30^\circ)] \hat{\mathbf{a}}_\theta \\
&\quad [-22.65 \sin(45^\circ) + 6.80 \cos(45^\circ)] \hat{\mathbf{a}}_\phi \\
&= [8.01 + 2.40 - 9.85] \hat{\mathbf{a}}_r + [13.87 + 4.16 + 5.69] \hat{\mathbf{a}}_\theta + [-16.02 + 4.81] \hat{\mathbf{a}}_\phi \text{ [m]} \\
&= 0.56 \hat{\mathbf{a}}_r + 23.72 \hat{\mathbf{a}}_\theta - 11.21 \hat{\mathbf{a}}_\phi \text{ [m]}
\end{aligned}$$

(2) Solution:



$$(a) \quad \mathbf{E}(0,0,h) = \int \frac{\rho_L dl}{4\pi\epsilon_0 R^2} \hat{\mathbf{a}}_R$$

$$= \frac{\rho_L}{4\pi\epsilon_0} \int \frac{dl}{R^3} \mathbf{R}$$

$$\text{where: } \hat{\mathbf{a}}_R = \mathbf{R} / R$$

$$\mathbf{R} = -a \hat{\mathbf{a}}_\rho + h \hat{\mathbf{a}}_z$$

$$R = |\mathbf{R}| = (a^2 + h^2)^{1/2}$$

$$dl = a d\phi$$

$$\begin{aligned}
&= \frac{\rho_L}{4\pi\epsilon_o} \int_0^{2\pi} \frac{a d\phi}{(a^2 + h^2)^{3/2}} (-a\hat{\mathbf{a}}_\rho + h\hat{\mathbf{a}}_z) \\
&= \frac{-\rho_L}{4\pi\epsilon_o} \int_0^{2\pi} \frac{a^2}{(a^2 + h^2)^{3/2}} \hat{\mathbf{a}}_\rho d\phi + \frac{\rho_L}{4\pi\epsilon_o} \int_0^{2\pi} \frac{a h}{(a^2 + h^2)^{3/2}} \hat{\mathbf{a}}_z d\phi \\
&= \frac{-\rho_L a^2}{4\pi\epsilon_o (a^2 + h^2)^{3/2}} \int_0^{2\pi} \hat{\mathbf{a}}_\rho d\phi + \frac{\rho_L a h}{4\pi\epsilon_o (a^2 + h^2)^{3/2}} \hat{\mathbf{a}}_z \int_0^{2\pi} d\phi
\end{aligned}$$

Note: The unit vector $\hat{\mathbf{a}}_\rho$ changes its direction with ϕ so it must be properly integrated. This is the reason why it is not taken outside the integration sign. However, the unit vector $\hat{\mathbf{a}}_z$ can be taken out because it does not change its direction with angle ϕ .

Since $\hat{\mathbf{a}}_\rho = \cos \phi \hat{\mathbf{a}}_x + \sin \phi \hat{\mathbf{a}}_y$, the above may be rewritten as:

$$\mathbf{E}(0,0,h) = \frac{-\rho_L a^2}{4\pi\epsilon_o (a^2 + h^2)^{3/2}} \left[\int_0^{2\pi} \cos \phi \hat{\mathbf{a}}_x d\phi + \int_0^{2\pi} \sin \phi \hat{\mathbf{a}}_y d\phi \right] + \frac{\rho_L a h}{4\pi\epsilon_o (a^2 + h^2)^{3/2}} \hat{\mathbf{a}}_z \int_0^{2\pi} d\phi$$

$\hat{\mathbf{a}}_x$ and $\hat{\mathbf{a}}_y$ do not change directions as ϕ varies, so they can be moved outside the integration:

$$\begin{aligned}
\mathbf{E}(0,0,h) &= \frac{-\rho_L a^2}{4\pi\epsilon_o (a^2 + h^2)^{3/2}} \left[\hat{\mathbf{a}}_x \int_0^{2\pi} \cos \phi d\phi + \hat{\mathbf{a}}_y \int_0^{2\pi} \sin \phi d\phi \right] + \frac{\rho_L a h}{4\pi\epsilon_o (a^2 + h^2)^{3/2}} \hat{\mathbf{a}}_z 2\pi \\
&= \frac{-\rho_L a^2}{4\pi\epsilon_o (a^2 + h^2)^{3/2}} \left[\hat{\mathbf{a}}_x \sin \phi \Big|_0^{2\pi} - \hat{\mathbf{a}}_y \cos \phi \Big|_0^{2\pi} \right] + \frac{\rho_L a h}{2\epsilon_o (a^2 + h^2)^{3/2}} \hat{\mathbf{a}}_z \\
&= \frac{-\rho_L a^2}{4\pi\epsilon_o (a^2 + h^2)^{3/2}} \left[\hat{\mathbf{a}}_x 0 - \hat{\mathbf{a}}_y 0 \right] + \frac{\rho_L a h}{2\epsilon_o (a^2 + h^2)^{3/2}} \hat{\mathbf{a}}_z \\
&= \frac{\rho_L a h}{2\epsilon_o (a^2 + h^2)^{3/2}} \hat{\mathbf{a}}_z = \frac{\rho_L a h}{2\epsilon_o (h^2 + a^2)^{3/2}} \hat{\mathbf{a}}_z \quad [\text{V/m}] \quad (\text{as expected!})
\end{aligned}$$

Obviously, contributions along $\hat{\mathbf{a}}_\rho$ add up to zero. However, the result was obtained without invoking symmetry.